



Data Structures

Linear Structure

Linear List

Definition

$$L = \begin{cases} (a_0, a_1, \dots, a_{n-1}) & n \geq 1 \\ () & n = 0 \end{cases}$$



- ✓
- ✓
- ✓
- ✓

a_0
 a_{n-1}
 a_i

Arrays

A set of pairs: **<index, value>**
correspondence or mapping

Two operations:
Retrieve
Store

Array can be used to implement other abstract data types

The simplest one might be: **Ordered or linear list**

Operations () on linear list, including

- 1 Find the length n of the list
- 2 Read the list from left to right (or right to left)
- 3 Retrieve the i th element, $0 \leq i < n$
- 4 Store a new value into the i th position, $0 \leq i < n$
- 5 Insert a new element at the position i , $0 \leq i < n$
 $i, i+1, \dots, n-1$ to $i+1, i+2, \dots, n$
- 6 Delete the element at position i , $0 \leq i < n$
 $i+1, i+2, \dots, n-1$ to $i, i+1, \dots, n-2$

Linear List ADT or GeneralArray

```

class      {
public:
    int      ;
    void     ;
    float    int ;
    void     int float ;
    void     int float ;
    float    int ;
};

```

Generally specified as a C++ (template) class

How to represent ordered list efficiently?

- Sequential mapping
 - Use array : $a_i \leftrightarrow \text{index } i$
- Complexity
 - Random access any element, $T(n) = O(1)$

```

float Retrieve(int i);
// if (i∈IndexSet) return the float associated with i in the
// array;else throw an exception.

void Store(int i, float x);
// if (i∈IndexSet) replace the old value associated with i
// by x; else throw an exception.

```

Operations **Insert** and **Delete**

```
void Insert(int i, float x);  
// insert x as the indexth element, elements  
// with theIndex >= index have their index increased by 1  
  
void Delete(int i);  
// remove and return the indexth element,  
// elements with higher index have their index reduced by 1
```

Insert

```
template <typename T>  
bool Insert (T data[], int i, T x)  
{  
    //      x      i (1<=i<=n+1)  
  
    if (n == maxSize) return false; //  
    if (i < 1 || i > n+1) return false; // i  
    for (int j = n; j >= i; j--) // ,  
        data[j] = data[j-1]; // ( i data[i-1] )  
    data[i-1] = x;  
    n++;  
  
    return true; //  
};
```

Analysis

Insert into *i*th position, need move backward from *data*[*i*-1] to *data* [*n*-1]

$$n-1-(i-1)+1 = n-i+1$$

Average Moving Number

when $p_i = 1/n$, and for all position, $1 \leq i \leq n$

$$\begin{aligned} \text{AMN} &= \frac{1}{n+1} \sum_{i=1}^{n+1} (n-i+1) = \frac{1}{n+1} (n + \dots + 1 + 0) \\ &= \frac{1}{(n+1)} \frac{n(n+1)}{2} = \frac{n}{2} \end{aligned}$$

Remove

```
//          x
template <typename T>
bool Remove (T data[], int i, T & x)
{
    //          i (1<=i<=n)
    if (n == 0) return false; //
    if (i < 1 || i > n) return false; // i

    x = data[i-1];
    for (int j = i; j <= n-1; j++) // , ,
        data[j-1] = data[j];
    n--;

    return true;
};
```

Analysis

- If removed the i th term, need to move forward from $i+1$ th to n th

$$n - (i+1) + 1 = n - i$$

- AMN :

$$AMN = \frac{1}{n} \sum_{i=1}^n (n - i) = \frac{1}{n} \frac{(n-1)n}{2} = \frac{n-1}{2}$$

- when $p_i = 1/n$, and $1 \leq i \leq n$

Search

```
typedef int T; //
int search(T data[], int Size, T & x)
{
    //          x
    //
    //
    for (int i = 1; i <= Size; i++)
        if (data[i-1] == x) return i;
    //          1

    return 0; //
};
```

Analysis

Average Comparing Number

Success:

$$ACN = \sum_{i=1}^n p_i \times c_i$$

when $p_i = 1/n$ ()

$$\begin{aligned} ACN &= \frac{1}{n} \sum_{i=1}^n i = \frac{1}{n} (1 + 2 + \dots + n) = \\ &= \frac{1}{n} * \frac{(1+n) * n}{2} = \frac{1+n}{2} \end{aligned}$$

Unsuccess : $ACN = n$



Data Structures

Polynomial

Polynomial ADT

```
class Polynomial {  
    //  $p(x) = a_0x^{e_0} + \dots + a_nx^{e_n}$   
    // a set of ordered pairs of  $\langle e_i, a_i \rangle$   
    // where  $a_i$  is a nonzero float coefficient  
    // and  $e_i$  is a non-negative exponent  
public:  
    Polynomial ();  
    // Construct the polynomial  $p(x) = 0$ 
```

```

void AddTerm (Exponent e, Coefficient c);
// add the term <e,c> to *this, so that it can be initialized

Polynomial Add (Polynomial poly);
// return the sum of the polynomials *this and poly

Polynomial Mult (Polynomial poly);
// return the product of the polynomials *this and poly

float Eval ( float f);
// evaluate polynomial *this at f and return the result
}

```

Polynomial Representation 1

private:

```

int degree;           // degree ≤ MaxDegree
float coef[MaxDegree+1];
a.degree = ?         // n
a.coef[i] = ?        // an-i, 0 ≤ i ≤ n

// Simple algorithms for many operations

```

When **a.degree** << **MaxDegree**, representation 1 is very poor in memory use.

Polynomial Representation 2

To improve, define variable sized data member as:

private:

```

int degree;
float *coef; //

```

Polynomial::Polynomial(int d)

```

{
  int degree=d;
  coef= new float[degree+1]; //
}

```

Polynomial Representation 3

```
class Polynomial; // forward declaration
class Term {
    friend Polynomial;
private:
    float coef; // coefficient
    int exp; // exponent
};
class Polynomial {
public:
    // .....
private:
    Term *termArray;
    int capacity; // size of termArray
    int terms; // number of nonzero terms
};
```

Addition

Use presentation 3 to obtain $C = A + B$

$$A(x) = 3x^2 + 2x + 4$$

$$B(x) = x^4 + 10x^3 + 3x^2 + 1$$

Idea:

- ✓ Because the exponents are in descending order, can add $A(x)$ and $B(x)$ term by term to $C(x)$
- ✓ The terms of C are entered into its *termArray* by calling function **NewTerm**
- ✓ If the space in *termArray* is not enough, its capacity is doubled

```
Polynomial Polynomial::Add (Polynomial b)
{ // return the sum of the polynomials *this and b
    Polynomial c;
    int aPos=0, bPos=0;
    while (( aPos < terms) && (b < b.terms))
        if (termArray[aPos].exp==b.termArray[bPos].exp) {
            float t = termArray[aPos].coef + termArray[bPos].coef
            if ( t ) c.NewTerm (t, termArray[aPos].exp);
            aPos++; bPos++;
        }
        else if (termArray[aPos].exp < b.termArray[bPos].exp) {
            c.NewTerm (b.termArray[bPos].coef, b.termArray[bPos].exp);
            bPos++;
        }
}
```

```

else {
    c.NewTerm (termArray[aPos].coef, termArray[aPos].exp);
    aPos++;
}
} // end of while
// add in the remaining terms of *this
for ( ; aPos < terms; aPos++ )
    c.NewTerm(termArray[aPos].coef, termArray[aPos].exp );
// add in the remaining terms of b
for ( ; bPos < b.terms; bPos++ )
    c.NewTerm(b.termArray[bPos].coef, b.termArray[bPos].exp);
return c;
}

```

```

void Polynomial::NewTerm(const float theCoeff, const int theExp)
{ // add a new term to the end of termArray
    if (terms == capacity)
    { // double capacity of termArray
        capacity *= 2;
        term *temp = new term[capacity]; // new array
        copy(termArray, termArray + terms, temp);
        delete [] termArray; // deallocate old memory
        termArray = temp;
    }
    termArray[terms].coef = theCoeff;
    termArray[terms].exp = theExp;
}

```



Data Structures

Matrix

Teacher : Wang Wei

1. Ellis Horowitz, etc., Fundamentals of Data Structures in C++
2. ,
3. <http://inside.mines.edu/~dmehta/>
4. ,

Representation

A natural way

- ✓ `a[m][n]`
- ✓ access element by `a[i][j]`, easy operations
- ✓ **But** for sparse matrix, wasteful of both memory and time

Alternative way

- ✓ store nonzero elements explicitly
- ✓ 0 as default

Sparse Matrix ADT

```
class SparseMatrix
{ // a set of <row, column, value>, where row, column are
  // non-negative integers and form a unique combination;
  // value is also an integer.
public:
  SparseMatrix ( int r, int c, int t);
  // creates a rxc SparseMatrix with a capacity of t nonzero
  // terms
  SparseMatrix Transpose ();
  // return the SparseMatrix obtained by transposing *this
  SparseMatrix Add ( SparseMatrix b);
  SparseMatrix Multiply ( SparseMatrix b);
};
```

Sparse Matrix Representation

- ✓ Triple *<row, col, value>*
- ✓ Sorted in ascending order by *<row, col>*

```
class SparseMatrix;
class MatrixTerm
{
  friend class SparseMatrix;
private:
  int row, col, value;
};
```

- ✓ Need also
 - the **number** of rows
 - the **number** of columns
 - the **number** of nonzero elements
- ✓ in class SparseMatrix
 - private:
 - int** rows, cols, terms, capacity;
 - MatrixTerm *smArray;

Triple representation

	0	1	2	3	4	5
0	15	0	0	22	0	-15
1	0	11	3	0	0	0
2	0	0	0	-6	0	0
3	0	0	0	0	0	0
4	0	0	0	0	0	0
5	0	0	28	0	0	0

val	row	col
15	0	0
22	0	3
15	0	5
11	1	1
3	1	2
-6	2	3
28	3	2

Transposing () a Matrix

- ✓ 2-dimensional () representation
- ✓ if an element is at position **[i][j]** in the original matrix
- ✓ then it is at position **[j][i]** in the transposed matrix

```

for (int j=0; j < columns; j++)
  for (int i=0; i < rows; i++)
    B[j][i] = A[i][j];

```

$T(n) = O(\text{cols} * \text{rows})$

	row	col	value		smArray	row	col	value
smArray[0]	0	0	15		[0]	0	0	15
[1]	0	3	22		[1]	0	4	91
[2]	0	5	-15		[2]	1	1	11
[3]	1	1	11		[3]	2	1	3
[4]	1	2	3	→	[4]	2	5	28
[5]	2	3	-6		[5]	3	0	22
[6]	4	0	91		[6]	3	2	-6
[7]	5	2	28		[7]	5	0	-15

First try the transpose :

for (each row i)

✓ take element (i, j, value)

✓ store it in (j, i, value)

Improvement: for (all elements in col j)

store (i, j, value) of the original matrix

as (j, i, value) of the transpose

➤ Since the rows are in order

➤ so $smArray[j][i] = originalMatrix[i][j]$

FastTranspose Algorithm

Step1: get Acol value

Acol is the number of elements in each column of ***this**

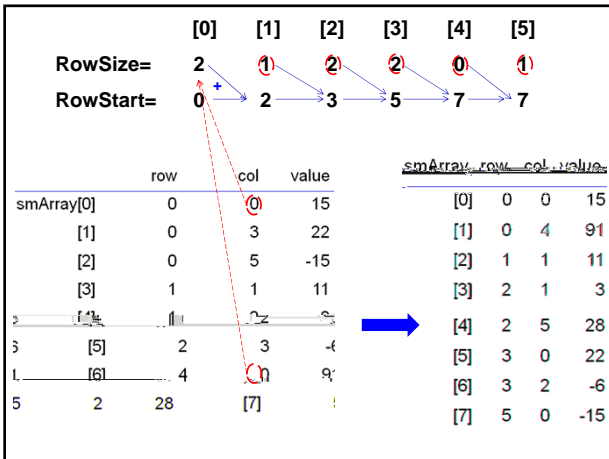
Step2: Brow = Acol

Brow is the number of elements in each row of **B**

Step3: obtain Bstart

Bstart is the starting point in **B** of each of its rows

Step4: move the elements of ***this** one by one into their **right position** in **B**



SparseMatrix SparseMatrix::FastTranspos ()

*// return the transpose of *this in O(terms+cols) time*

SparseMatrix b(cols, rows, terms);

if (terms > 0)

{ *// nonzero matrix*

int *rowSize = new int[cols];

int *rowStart = new int[cols];

// compute rowSize[i] = number of terms in row i of b

fill(rowSize, rowSize + cols, 0); *// initialize*

for (i=0; i<terms; i++) rowSize[smArray[i].col]++;

```

// rowStart[i] = starting position of row i in b
rowStart[0] = 0;
for (i=1;i<cols;i++) rowStart[i]=rowStart[i-1]+rowSize[i-1];
for (i=0; i<terms; i++)
{
    // copy from *this to b
    int j = rowStart[smArray[i].col];
    b.smArray[j].row = smArray[i].col;
    b.smArray[j].col = smArray[i].row;
    b.smArray[j].value = smArray[i].value;
    rowStart[smArray[i].col]++;
} // end of for
delete [ ] rowSize; delete [ ] rowStart;
} // end of if
return b;
}

```



Data Structures

Strings

Teacher : Wang Wei

1. Ellis Horowitz, etc., Fundamentals of Data Structures in C++
2. ,
3. <http://inside.mines.edu/~dmehta/>
4. ,

String ADT

- > A string $S = s_0, s_1, \dots, s_{n-1}$
- > where $s_i \in \text{char}$, $0 \leq i < n$, n is the length

class String

```

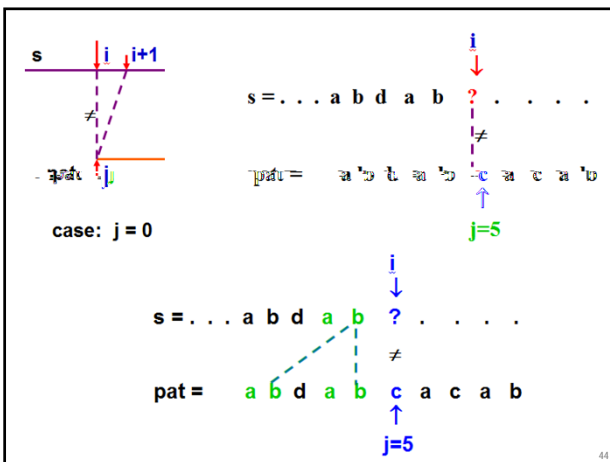
{ // a finite set of zero or more characters
public:
    String (char *init, int m);
    // initialize *this to string init of length m

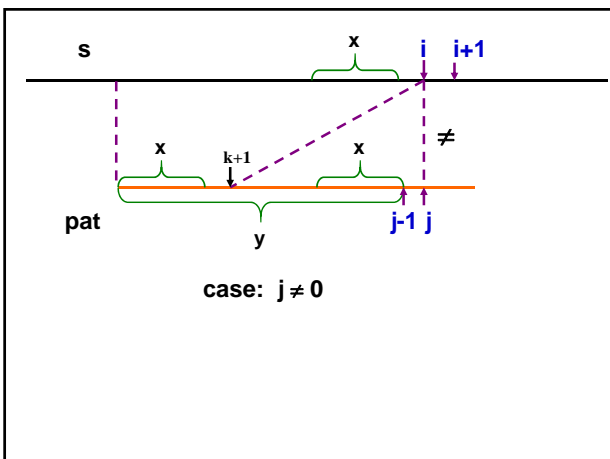
```

```
bool operator == (String t);
    // if *this equals t, return true else false
bool operator ! ( );
    // if *this is empty return true else false
int Length ( );
    // return the number of chars in *this
String Concat (String t);
String Substr (int i, int j);
int Find (String pat);
    // return i such that pat matches the substring of *this that begins
```

String Pattern Matching: **KMP** Algorithm

- ✓ **KMP** : Knuth-Morris-Pratt
- ✓ This is optimal for B-F algorithm
 - ✓ *avoid rescanning* ?
 - ✓ $O(\text{LengthP} + \text{LengthS})$?
 - ✓ in the worst it is necessary to look at characters in the pattern and string at least once
- ✓ Determine **where to continue the search** and **avoid moving backwards** in the string





```
void String::Failurefunction()
{
    // compute the failure function of the pattern *this
    int LengthP= Length();
    f [0]= -1;
    for (int j=1; j< LengthP; j++)    // compute f[j]
    { int i=f [j-1];
      while ( (str[j]!=str[i+1]) && (i>=0)) i=f[i]; // try for m
      if ( str[j]==str[i+1]) f[j]=i+1; // fm(j-1)+1
      else f[j]= -1;
    }
}
```
